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Simulated By MATLAB Software (Mittal And Nagrath, 2003). (a) (b) Fig. 2: Link Kinematic Of Right Arm In Position 1 (a) (b) Fig. 3: Link Kinematic Of Right Arm In Position 2 In Fig. 2a It Shows Exoskeleton Suit For Right Arm With Joint Angle θ_{z1} And With Link Twist α_{z1} In Fig. 2b. The Angle θ_{z0} Is Attached With Human Body. Jul 2th, 2024

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The Exoskeleton, Simulation Was Performed In SOLIDWORKS Motion Analysis Environment. Fig-1: 3D Representation Of Exoskeleton 2.1 Actuation Actuation Is The Major Part Of Exoskeleton. For This Work, Two Mar 3th, 2024

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