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Linear Algebra MA 631-2E, Fall 2019 Instructor: Dr. Y. Zeng, UH 4012 Time & Location: TR, 2PM { 3:15PM, UH 4002 ffi Hours: Tuesdays 3:30PM{4:30PM (or By Appointment) Text: A Set Of Class Notes (evolved From Courses Taught By Several Faculty Members In The Department) Will Be Provided. These Notes Contain All De Nititions, Theorems, And Examples, 2th, 2024

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6 6 4 1 0 0 0 1 0 0 0 0 3 0 0 0 0 3 3 7 7 5. The Diagonal Matrix Has Determinant 9. The Row Operations We Did Were Both Type 1 Which Changes The Sign, But Since We Did 2 Of Them The Sign Changed Twice So AT A Also Has Determinant 9. 4. Let  $A = \begin{pmatrix} 2 & 4 & 1 & 0 & 3 & 2 & 1 & 6 & 1 & 1 & 4 & 3 & 5 \end{pmatrix}$ . (a) Find  $A^{-1}$  Or Show That A Is Not Invertible. (12 Pts) 1th, 2024

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Problem S03.8. Let  $V$  Be An  $N$ -dimensional Complex Vector Space And  $T : V \rightarrow V$  A Linear Operator. Suppose That The Characteristic Polynomial Of  $T$  Has  $N$  distinct Roots. Show That There Is A Basis  $B$  Of  $V$  Such That The Matrix Representation Of  $T$  In The Basis  $B$  Is Diagonal. Solution. Since Each Root Of The Characteristic Polynomial (and Thus Each Eigenvalue ... 3th, 2024

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(2) ( T / F ) If A And B Are Square Matrices Then  $(A + B)^2 = A^2 + 2AB + B^2$ . (3) ( T / F ) The Angle Between Two Nonzero Vectors In  $\mathbb{R}^n$  Is Less Than 90 Degrees I 1th, 2024

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MA 242 LINEAR ALGEBRA C1, Solutions To First Midterm Exam Prof. Nikola Popovic, October 5, 2006, 09:30am - 10:50am Problem 1 (15 Points). Determine H And K Such That The Solution Set Of  $x_1 + 3x_2 = k$   $4x_1 + hx_2 = 8$  (a) Is Empty, (b) Contains A Unique Solution, And (c) Contains Infinitely Many Solutions. (Give Separate Answers For Each Part, And ... 1th, 2024

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$x$  Is An  $n \times 1$  Vector. A System Of Linear Equations, Also Referred To As Linear Map, Can Therefore Be Identified With A Matrix, And Any Matrix Can Be Identified With ("turned Into") A Linear System. In Order To Study Linear Systems, We Study Matrices And Their Properties. 2 Matrices 2.1 Basic Mat 1th, 2024

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## **Math 2331 Linear Algebra - 1.7 Linear Independence**

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## **Some Linear Transformations On $\mathbb{R}^2$ Math 130 Linear Algebra**

That's An Expansion By A Factor Of 2. Note That Every Vector Is A 2-eigenvector. In Other Words, All Of  $\mathbb{R}^2$  Is The 2-eigenspace. Figure 6: Expansion Figure 7: Contraction Figure 8: Half Turn A Scalar Matrix Is A Multiple Of The Identity Matrix Like T 1th, 2024

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