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More Formally, A Problem Is Defined By: 1. A Set Of States S 2. An Initial State $S_I \in S$ 3. A Set Of Actions A — $S \rightarrow A$ Actions(s) = The Set Of Actions That Can Be Executed In S , That Are Applicable In S . 4. Transition Model: $S \times A \rightarrow S$ Result(s, A) $S \rightarrow R$ — $s \rightarrow R$ Is Called A Successor Of S — {s | 1th, 2024

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