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Configuration As Explained In [5]. 2. Place The Gyroscope Module On Top Of The SRV02 Plant Such That The Servo Output Shaft Inserts The Hole On The Bottom Platform Of The Gyroscope Module And It Can Freely Rotate About The Shaft. 3th, 2024

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2. References [1] NI-ELVIS User Manual [2] DCMCT User Manual [3] QNET Experiment #01: DC Motor Speed Control 3. DCMCT Plant Presentation 3.1. Component Nomenclature As A Quick Nomenclature, Table 1, Below, Provides A List Of The Principal Elements Composing The DC Motor Control Trainer (DCMCT) System. Every Element Is Located And 2th, 2024

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